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Chapter 1 : Principles of Statics and Dynamics, 10th Edition

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The International System of Units. Vector Addition of Forces. Addition of a System of Coplanar Forces. Addition and Subtraction of Cartesian Vectors. Force Vector Directed Along a Line. Equilibrium of a Particle. Condition for the Equilibrium of a Particle. Moment of a Force—Scalar Formulation. Moment of a Force—Vector Formulation. Moment of a Force About a Specified Axis. Moment of a Couple. Resultants of a Force and Couple System. Further Reduction of a Force and Couple System. Reduction of a Simple Distributed Loading. Equilibrium of a Rigid Body. Conditions for Rigid-Body Equilibrium. Equilibrium in Two Dimensions. Two- and Three-Force Members. Equilibrium in Three Dimensions. Constraints for a Rigid Body. The Method of Joints. The Method of Sections. Internal Forces Developed in Structural Members. Shear and Moment Equations and Diagrams. Characteristics of Dry Friction. Problems Involving Dry Friction. Frictional Forces on Screws. Frictional Forces on Flat Belts. Frictional Forces on Journal Bearings. Center of Gravity and Centroid. Theorems of Pappus and Guldinus. Resultant of a General Distributed Force System. Definitions of Moments of Inertia for Areas. Parallel-Axis Theorem for an Area. Radius of Gyration of an Area. Moments of Inertia for an Area by Integration. Moments of Inertia for Composite Areas. Product of Inertia for an Area. Mass Moment of Inertia. Definition of Work and Virtual Work. Potential Energy Criterion for Equilibrium. Numerical and Computer Analysis. Kinematics of a Particle. Motion of a Projectile. Normal and Tangential Components. Kinetics of a Particle: The Equation of Motion. Equation of Motion for a System of Particles. Normal and Tangential Coordinates. Central-Force Motion and Space Mechanics. The Work of a Force. Principle of Work and Energy. Principle of Work and Energy for a System of Particles. Conservative Forces and Potential Energy. Principle of Linear Impulse and Momentum. Conservation of Linear Momentum for a System of Particles. Angular Impulse and Momentum Principles. Propulsion with Variable Mass. Planar Kinematics of a Rigid Body. Rotation About a Fixed Axis. Absolute General Plane Motion Analysis. Instantaneous Center of Zero Velocity. Planar Kinetics of a Rigid Body: Planar Kinetic Equations of Motion. The Work of a Couple. Linear and Angular Momentum. Principle of Impulse and Momentum. Three-Dimensional Kinematics of a Rigid Body. Rotation About a Fixed Point. Three-Dimensional Kinetics of a Rigid Body. Moments and Products of Inertia. Viscous Damped Free Vibration. Viscous Damped Forced Vibration. Review for the Fundamentals of Engineering Examination. Answers to Selected Problems.

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Book Preface OBJECTIVES The main objective of a first course in mechanics should be to develop in the engineering student the ability to analyze any problem in a simple and logical manner and to apply to its solution a few, well-understood, basic principles. It is hoped that this text, as well as the preceding volume, *Vector Mechanics for Engineers: Statics*, will help the instructor achieve this goal. Similarly, the concept of vector differentiation will be introduced early in this volume, and vector analysis will be used throughout the presentation of dynamics. This approach leads to more concise derivations of the fundamental principles of mechanics. It also makes it possible to analyze many problems in kinematics and kinetics which could not be solved by scalar methods. The emphasis in this text, however, remains on the correct understanding of the principles of mechanics and on their application to the solution of engineering problems, and vector analysis is presented chiefly as a convenient tool. One of the characteristics of the approach used in this book is that mechanics of particles is clearly separated from the mechanics of rigid bodies. This approach makes it possible to consider simple practical applications at an early stage and to postpone the introduction of the more difficult concepts. The statics of rigid bodies is considered later, at which time the vector and scalar products of two vectors were introduced and used to define the moment of a force about a point and about an axis. The basic concepts of force, mass, and acceleration, of work and energy, and of impulse and momentum are introduced and first applied to problems involving only particles. Thus, students can familiarize themselves with the three basic methods used in dynamics and learn their respective advantages before facing the difficulties associated with the motion of rigid bodies. Since this text is designed for the first course in dynamics, new concepts are presented in simple terms and every step is explained in detail. On the other hand, by discussing the broader aspects of the problems considered, and by stressing methods of general applicability, a definite maturity of approach has been achieved. For example, the concept of potential energy is discussed in the general case of a conservative force. Also, the study of the plane motion of rigid bodies is designed to lead naturally to the study of their general motion in space. This is true in kinematics as well as in kinetics, where the principle of equivalence of external and effective forces is applied directly to the analysis of plane motion, thus facilitating the transition to the study of three-dimensional motion. The fact that mechanics is essentially a deductive science based on a few fundamental principles is stressed. Derivations have been presented in their logical sequence and with all the rigor warranted at this level. However, the learning process being largely inductive, simple applications are considered first. The tenth edition of *Vector Mechanics for Engineers* retains the unified presentation of the principles of kinetics which characterized the previous nine editions. The concepts of linear and angular momentum are introduced in Chap. This makes possible an earlier introduction of the principle of conservation of angular momentum and a more meaningful discussion of the motion of a particle under a central force Sec. More importantly, this approach can be readily extended to the study of the motion of a system of particles Chap.

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